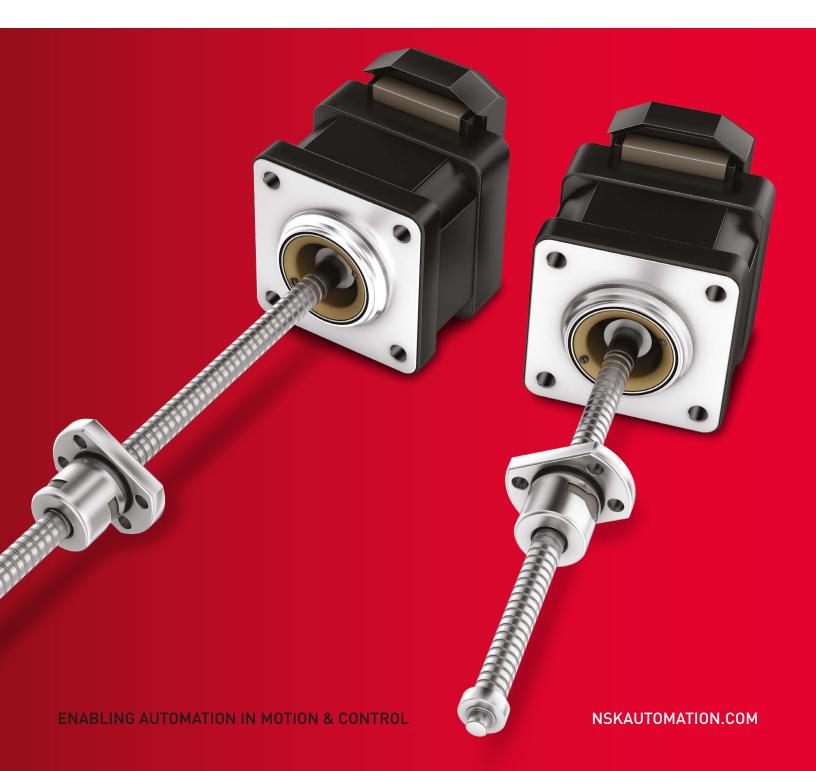


MBSA MOTORIZED BALL SCREW ACTUATOR

INTEGRATED PRECISION FOR MEDICAL DEVICES AND EQUIPMENT





ENABLING AUTOMATION

NSK MECHATRONIC SYSTEM SOLUTIONS

For decades, NSK has specialized in developing electromechanical solutions – integrating our precision machine components with control technology – to deliver advanced, reliable and precise motion and control.

Robotic surgery. Medical imaging. Biomedicine. Semiconductor. 3D printing. Factory automation. Our customers are vast and diverse, united by precision-critical applications and NSK's ability to achieve coherent mechatronic solutions that offer:

- › Augmented machine function and accuracy
- > Optimized system performance, space and life
- Reduced costs and complexity

From complex systems to single-axis solutions, NSK delivers innovative and ideal integrated motion solutions to enable automation and accuracy in machine function, for a competitive edge to our customers.



EFFICIENT, PRECISE LINEAR MOTION – MBSA

Nowhere is the stringent need for smooth, precise, repeatable and reliable motion more critical than with medical devices and equipment. In applications ranging from diagnostics and dispensing to imaging and scanning, a common challenge emerges: to translate the rotary motion of a motor into highly accurate and smoothly controlled linear motion within increasingly compact spaces.

Enter NSK, and the MBSA Series Motorized Ball Screw Actuator.

Compact and fully integrated, the MBSA delivers exponentially superior accuracy and efficiency. It's the result of our global expertise in precision ball screws and mechatronic integration, and reflects the unwavering commitment behind all NSK automation initiatives:

- > Streamline consolidating multiple components into a single, compact and coherent solution
 - Simplify reducing installation complexity and eliminating potential alignment errors
 - Support dedicated collaboration, project management and technical expertise

DESIGN AND OPERATIONAL BENEFITS

NSK's MBSA Series Motorized Ball Screw Actuator is a fully integrated, highly compact and high-performing solution for precision-critical medical devices and laboratory equipment. With smooth friction-free motion, high-accuracy positioning and high operating efficiencies, it offers considerable advantages versus conventional solutions.



DESIGN FEATURES

- > Precision C3 accuracy ball screw directly integrated into a NEMA stepper motor
- > Available with ball screw shaft diameters of 6 and 8 mm, with leads of 1 and 2 mm
- > Screw shaft thread lengths range from 50 to 200 mm
- > Available with NEMA 14 and 17 size motors

- > A configurable encoder can be preassembled to the motor, allowing communication with a variety of controllers / drivers
- > Additional ball screw and motor frames are available upon request

RANGE OF AVAILABILITY

| | X |
|--|---|
|--|---|

| | MBSA SCREW SHAFT / MOTOR MODEL COMBINATIONS | | | | | | | | | | | |
|-----------------------|---|------|------|-----------------|---|---|------|--------------------------|----|--|--|--|
| SHAFT D | SHAFT DIAMETER 06 | | | 08 | | | | 10 | 12 | | | |
| STEPPER | MOTOR | NEM/ | A 14 | NEMA 14 NEMA 17 | | | NEM. | A 23 | | | | |
| SHAFT L | EAD | 1 | 2 | 1 | 2 | 1 | 2 | TBD | | | | |
| | 50 | | | | | | | | | | | |
| . LENGTH | 100 | | | | | | | | | | | |
| THREADED SHAFT LENGTH | 125 | | | | | | | Series Availability 2021 | | | | |
| THREADE | 150 | | | | | | | | | | | |
| | 200 | | | | | | | | | | | |

MBSA motorized ball screw actuators are standardly available from stock in the combinations shown in the table above.

shaft diameter / stepper motor / shaft lead combinations available

For additional combinations of screw shaft and/or motor sizes, please consult NSK.

PROVEN ADVANTAGES

- Integrated design eliminates alignment errors that can occur when the motor and ball screw are separately mounted
- Compact, space-saving solution with the elimination of a motor coupling
- > High accuracy positioning with zero backlash for precisioncritical medical devices and equipment
- Longer life than conventional lead screw designs due to reduced friction, reduced wear and dramatically higher efficiency - as high as 95%
- Energy efficient with reduced motor size and lower energy consumption
- > Smooth and quiet operation with improved rigidity
- > Easy installation, simplifying field replacement

DESIGN AND OPERATIONAL BENEFITS

ENGINEERED FOR EXTREME ACCURACY AND EFFICIENCY

SMOOTH ROTARY TO LINEAR MOTION

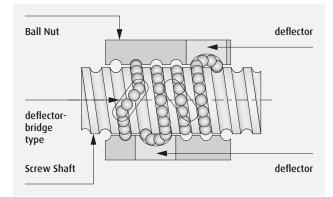
With the MBSA motorized ball screw actuator, NSK achieves superior performance by utilizing a C3 accuracy precision ball screw and rolling contact with precision balls, rather than the sliding contact of conventional lead screw solutions. The ball nut thread profile acts as an outer raceway and the screw shaft grooves act as an inner raceway with the balls travelling between.

The balls provide a rolling contact point between the nut and the shaft that dramatically lowers the coefficient of friction compared to a conventional lead screw solution. The result is a highly efficient (90% to 95%) mechanism that requires considerably less torque to convert rotary motion into linear motion. That translates into smooth, energy efficient and long-lasting performance.

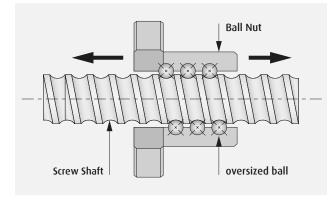
With size constraints in mind, MBSA ball nuts utilize bridge-type deflector recirculation to guide the balls between raceways, providing the essential recirculation in a compact space. Since the deflectors sit below the surface of the nut body outside diameter, this area can be used as a pilot surface for instruments or components attached to the nut.

POSITIONING ACCURACY WITH ZERO BACKLASH

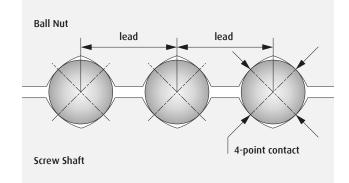
The inaccuracy created by backlash inherent to conventional lead screw solutions is completely eliminated with the MBSA. NSK uses slightly oversized balls to create a light preload, eliminating any axial play between the screw shaft and the nut. The elastic deformation of the balls creates an internal force between the nut and the screw shaft to eliminate clearance. The result is precise linear movement of the object attached to the ball screw nut, with zero backlash between shaft rotation and nut linear movement. This preload enables the high positioning accuracy and control that is ideal for highly precise medical devices and laboratory equipment with multi-directional axial loads.



Illustrated above: deflector-type recirculation within the ball screw nut, including bridge-type deflection used in the MBSA motorized ball screw actuator

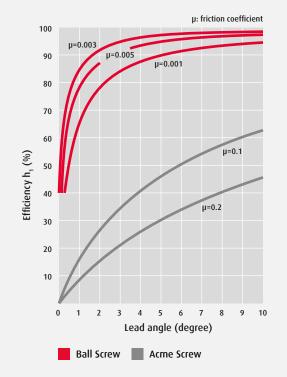


Illustrated above and below: by using slightly oversized balls resulting in 4 points of contact, NSK creates a light preload to eliminate clearance and possibility of backlash





Efficiency of Normal Operation: Converting Rotary Motion to Linear Motion



Illustrated above: comparative efficiencies of precision ground ball screws and lead screws

Using an NSK MBSA motorized ball screw actuator results in lower operating temperatures, smoother motion, reduced motor size and energy consumption, less wear and longer life compared to conventional lead screw solutions.

Ready to configure an MBSA motorized ball screw actuator? Visit **www.nskautomation.com**

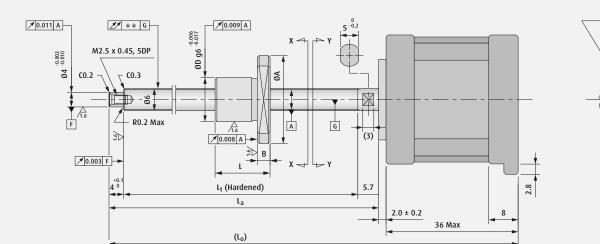
PRECISION MOTION AND CONTROL

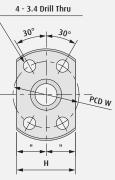
NSK C3 accuracy ball screws have a lead accuracy of 0.006 mm per shaft revolution. Over 300 mm of travel, the actual nut position deviation from the theoretical nut position is a maximum of 0.008 mm. Comparatively a lead screw can have a deviation as large as 0.250 mm, more than 30 times greater.



MBS06 WITH NEMA 14 STEPPER MOTOR

DIMENSIONS AND OPERATING VALUES





View X-X

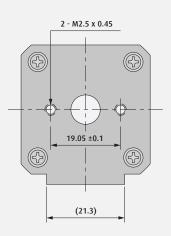
| MODEL NO. | BALL SCREW | | STROKE | | 9 | | | |
|-------------|------------|------|---------|----------------------|-----|-------|----------------|----|
| MUDEL NU. | Diameter | Lead | Nominal | Maximum ¹ | Lt | La | L _o | ØD |
| MBS0601050 | 6 | 1 | 30 | 35 | 50 | 59.7 | 97.7 | 12 |
| MBS0601100 | 6 | 1 | 80 | 85 | 100 | 109.7 | 147.7 | 12 |
| MBS0601125 | 6 | 1 | 105 | 110 | 125 | 134.7 | 172.7 | 12 |
| MB\$0602050 | 6 | 2 | 28 | 33 | 50 | 59.7 | 97.7 | 13 |
| MB\$0602100 | 6 | 2 | 78 | 83 | 100 | 109.7 | 147.7 | 13 |
| MB\$0602125 | 6 | 2 | 103 | 108 | 125 | 134.7 | 172.7 | 13 |

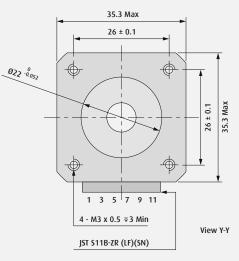
1) The value for maximum stroke is calculated as screw shaft dimension L, minus ball nut length dimension L

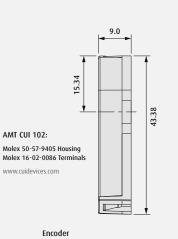
| NEMA 14 MOTOR SPECIFICATIONS | | | | | | | | |
|---|-------------------------|------------------|---------------|--|--|--|--|--|
| Number Of Phases 2 Phase Resistance 1.62 OHM +/-10% (20° C) | | | | | | | | |
| Step Angle | 1.8° | Phase Inductance | 2.2mH +/- 20% | | | | | |
| Rated Voltage | 2.43 V DC | Phase mouttainte | (1kHz 1V rms) | | | | | |
| Rated Current | 1.5 AMP | Rotor Inertia | 20 gcm^2 | | | | | |
| ueldie e Tereve | 0.23 Nm TYP (2 phase on | Motor Weight | 210 g | | | | | |
| Holding Torque | / rated current) | Insulation Class | B (130° C) | | | | | |

The permissible rotational speed for this ball screw and NEMA 14 motor is 1800 rpm or less.



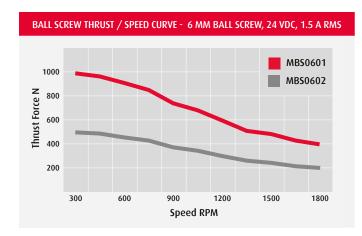






Note: Encoder adds 9 mm to overall length

| | BALL NUT DIME | INSIONS | | | | SHAFT | | |
|----|---------------|---------|----|----|---|-------|-------|---------|
| L | В | ØA | w | н | т | ер | vu | RUN-OUT |
| 15 | 3.5 | 24 | 18 | 16 | 0 | 0.008 | 0.008 | 0.020 |
| 15 | 3.5 | 24 | 18 | 16 | 0 | 0.008 | 0.008 | 0.020 |
| 15 | 3.5 | 24 | 18 | 16 | 0 | 0.010 | 0.008 | 0.025 |
| 17 | 4 | 25 | 19 | 17 | 0 | 0.008 | 0.008 | 0.020 |
| 17 | 4 | 25 | 19 | 17 | 0 | 0.008 | 0.008 | 0.020 |
| 17 | 4 | 25 | 19 | 17 | 0 | 0.010 | 0.008 | 0.025 |

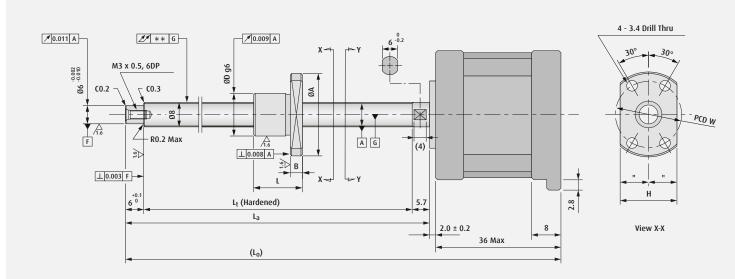


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MBS08 WITH NEMA 14 STEPPER MOTOR

DIMENSIONS AND OPERATING VALUES



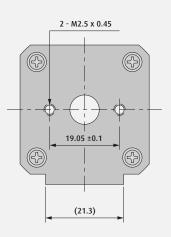
| | BALLS | SCREW | STR | OKE | | | | |
|-------------|----------|-------|---------|----------------------|-----|-------|-------|----|
| MODEL NO. | Diameter | Lead | Nominal | Maximum ¹ | Lt | La | Lo | ØD |
| MB\$0801050 | 8 | 1 | 29 | 34 | 50 | 61.7 | 99.7 | 14 |
| MB\$0801100 | 8 | 1 | 79 | 84 | 100 | 111.7 | 149.7 | 14 |
| MB\$0801125 | 8 | 1 | 104 | 109 | 125 | 136.7 | 174.7 | 14 |
| MB\$0801150 | 8 | 1 | 129 | 134 | 150 | 161.7 | 199.7 | 14 |
| MB\$0802050 | 8 | 2 | 19 | 24 | 50 | 61.7 | 99.7 | 16 |
| MB\$0802100 | 8 | 2 | 69 | 74 | 100 | 111.7 | 149.7 | 16 |
| MB\$0802125 | 8 | 2 | 94 | 99 | 125 | 136.7 | 174.7 | 16 |
| MB\$0802150 | 8 | 2 | 119 | 124 | 150 | 161.7 | 199.7 | 16 |
| MB\$0802200 | 8 | 2 | 169 | 174 | 200 | 211.7 | 249.7 | 16 |

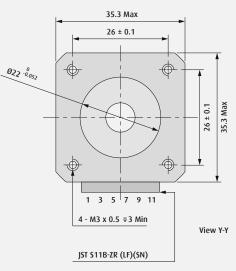
1) The value for maximum stroke is calculated as screw shaft dimension L_t minus ball nut length dimension L

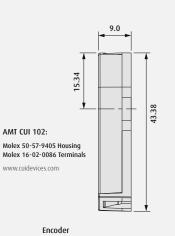
| NEMA 14 MOTOR SPECIFICATIONS | | | | | | | | |
|---|-------------------------|------------------|---------------|--|--|--|--|--|
| Number Of Phases 2 Phase Resistance 1.62 OHM +/-10% (20° C) | | | | | | | | |
| Step Angle | 1.8° | Phase Inductance | 2.2mH +/- 20% | | | | | |
| Rated Voltage | 2.43 V DC | Phase mouttainte | (1kHz 1V rms) | | | | | |
| Rated Current | 1.5 AMP | Rotor Inertia | 20 gcm^2 | | | | | |
| Holding Torque | 0.23 Nm TYP (2 phase on | Motor Weight | 210 g | | | | | |
| | / rated current) | Insulation Class | B (130° C) | | | | | |

The permissible rotational speed for this ball screw and NEMA 14 motor is 1800 rpm or less.



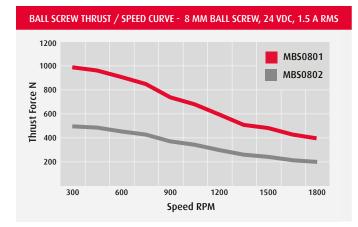






Note: Encoder adds 9 mm to overall length

| | BALL NUT DIME | INSIONS | | | | | SHAFT | |
|----|---------------|---------|----|----|---|-------|-------|---------|
| L | В | ØA | w | н | т | ер | vu | RUN-OUT |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.008 | 0.008 | 0.025 |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.008 | 0.008 | 0.025 |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.010 | 0.008 | 0.030 |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.010 | 0.008 | 0.030 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.008 | 0.008 | 0.025 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.008 | 0.008 | 0.025 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.010 | 0.008 | 0.030 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.010 | 0.008 | 0.030 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.010 | 0.008 | 0.030 |

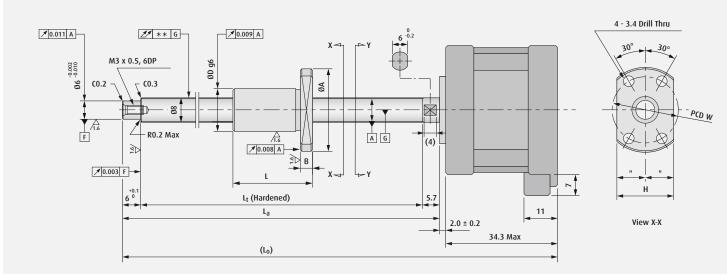


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MBS08 WITH NEMA 17 STEPPER MOTOR

DIMENSIONS AND OPERATING VALUES



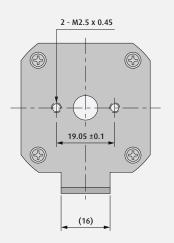
| MODEL NO. MBS0801050 MBS0801100 MBS0801125 MBS0801150 | BALL SCREW | | STR | STROKE | | SCREW SHAFT LENGTH | | | |
|---|------------|------|---------|----------------------|-----|--------------------|-----|----|--|
| MUDEL NU. | Diameter | Lead | Nominal | Maximum ¹ | Lt | La | Lo | ØD | |
| MB\$0801050 | 8 | 1 | 29 | 34 | 50 | 61.7 | 98 | 14 | |
| MB\$0801100 | 8 | 1 | 79 | 84 | 100 | 111.7 | 148 | 14 | |
| MB\$0801125 | 8 | 1 | 104 | 109 | 125 | 136.7 | 173 | 14 | |
| MB\$0801150 | 8 | 1 | 129 | 134 | 150 | 161.7 | 198 | 14 | |
| MB\$0802050 | 8 | 2 | 19 | 24 | 50 | 61.7 | 98 | 16 | |
| MB\$0802100 | 8 | 2 | 69 | 74 | 100 | 111.7 | 148 | 16 | |
| MB\$0802125 | 8 | 2 | 94 | 99 | 125 | 136.7 | 173 | 16 | |
| MB\$0802150 | 8 | 2 | 119 | 124 | 150 | 161.7 | 198 | 16 | |
| MB\$0802200 | 8 | 2 | 169 | 174 | 200 | 211.7 | 248 | 16 | |

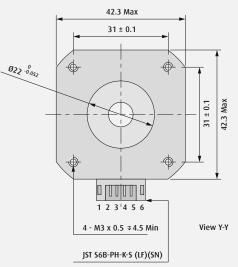
1) The value for maximum stroke is calculated as screw shaft dimension L_t minus ball nut length dimension L

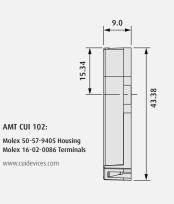
| NEMA 17 MOTOR SPECIFICATIONS | | | | | | | | |
|--|-------------------------|------------------|---------------------|--|--|--|--|--|
| Number Of Phases 2 Phase Resistance 1.7 0HM +/-10% (20° C) | | | | | | | | |
| Step Angle | 1.8° | Phase Inductance | 2.9mH +/- 20% (1kHz | | | | | |
| Rated Voltage | 2.55 V DC | Phase mouttainte | 1V rms) | | | | | |
| Rated Current | 1.5 AMP | Rotor Inertia | 38 gcm^2 | | | | | |
| | 0.32 Nm TYP (2 phase on | Motor Weight | 210 g | | | | | |
| Holding Torque | / rated current) | Insulation Class | B (130° C) | | | | | |

The permissible rotational speed for this ball screw and NEMA 17 motor is 1800 rpm or less.









Encoder

Note: Encoder adds 9 mm to overall length

| | BALL NUT DIME | INSIONS | | | | SHAFT | | |
|----|---------------|---------|----|----|---|-------|-------|---------|
| L | В | ØA | w | н | т | ер | vu | RUN-OUT |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.008 | 0.008 | 0.025 |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.008 | 0.008 | 0.025 |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.010 | 0.008 | 0.030 |
| 16 | 4 | 27 | 21 | 18 | 0 | 0.010 | 0.008 | 0.030 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.008 | 0.008 | 0.025 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.008 | 0.008 | 0.025 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.010 | 0.008 | 0.030 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.010 | 0.008 | 0.030 |
| 26 | 4 | 29 | 23 | 20 | 0 | 0.010 | 0.008 | 0.030 |

BALL SCREW THRUST / SPEED CURVE - 8 MM BALL SCREW, 24 VDC, 1.5 A RMS 1500 MBS0801 1250 MB\$0802 Thrust Force N 1000 750 500 250 300 600 900 1200 1500 1800 Speed RPM

Ready to configure an MBSA motorized ball screw actuator?

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DESIGNATION SYSTEM

08

01

02

Screw Shaft

Diameter

Shaft Lead

Screw Shaft Length

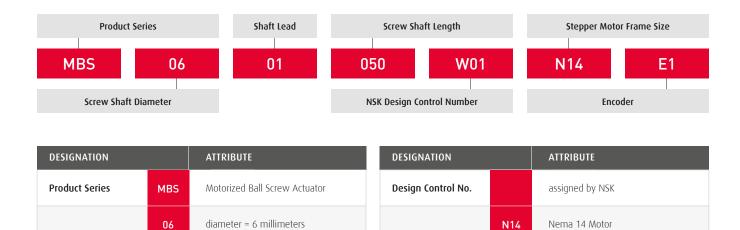
MBSA MOTORIZED BALL SCREW ACTUATORS

diameter = 8 millimeters

lead = 1 millimeter

lead = 2 millimeters

in millimeters, ranging from 50 to 200



Stepper Motor

N17

E1

E*

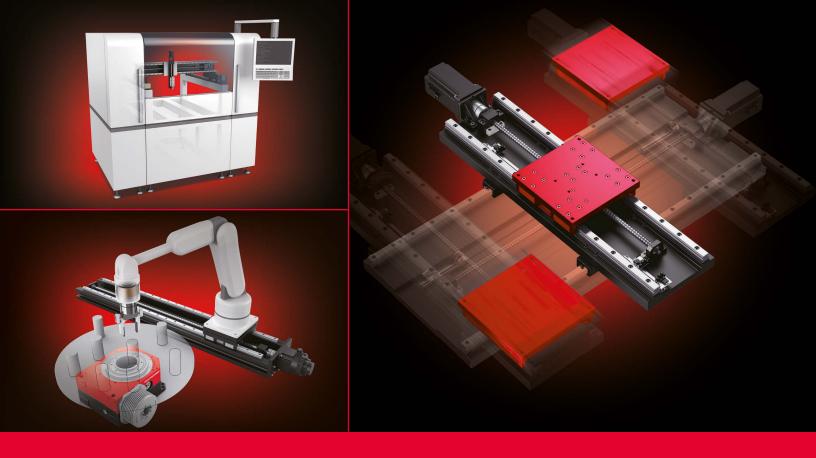
Nema 17 Motor

assigned by NSK

AMT CUI 102 Encoder Dip Switch

Frame Size

Encoder



ACCUMULATED EXPERTISE, OPTIMAL SUPPORT

For your precision machine component and integrated system requirements, you can rely on the optimum interaction of NSK design solutions, comprehensive engineering support, domestic manufacturing capabilities and access to our global technology network. Our local automation experts will collaborate closely with you through all aspects of design, provide intensive project management and extend comprehensive technical support. We aim to deliver to our customers the ideal motion and control solution and experience.

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